

Vector Autoregressions (VARs)

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- 3 Description of basic VAR models
- 4 Impulse response functions
- 5 Forecasting
- 6 Forecast error variance decomposition (FEVD)
- 7 Historical decomposition (HD)

- Seminal paper: Sims [1980] → Nobel-prize, 2011
- Estimation of VARs: Canova [2007]
- Structural VARs: Stock and Watson [2001] and Rubio-Ramirez et al. [2010]
- Bayesian VARs: Blake and Mumtaz [2012]

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 - 3 Forecast: Is the recovery sustainable or is there some probability of an other economic contraction?
 - 4 Data description: does unemployment help predict inflation better than the interest rate?

Motivating example

US Monetary Policy during 2001-2007

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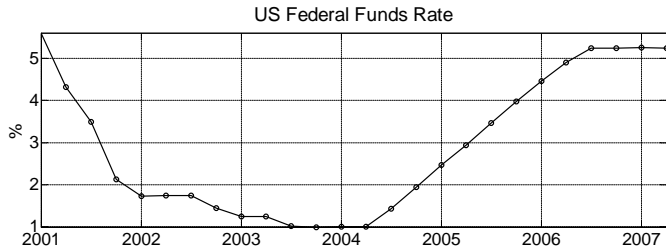
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Figure : Pre-crisis US Monetary Policy



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- First, it is unclear whether the low interest rates were a natural consequence of the Fed behaving optimally by responding to deteriorating business cycle conditions via cutting rates.
 - Could low rates be explained by the systematic part of policy, or were low rates in fact the result of non-systematic policy shocks?
 - Identifying monetary policy shocks and separating them from the systematic parts of policy is needed to understand historical interest rate dynamics.

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 - Could low rates be explained by the systematic part of policy, or were low rates in fact the result of non-systematic policy shocks?
 - Identifying monetary policy shocks and separating them from the systematic parts of policy is needed to understand historical interest rate dynamics.
- Second, it is unclear what the partial impact of monetary policy shocks has been on balance sheet expansions, given other factors (e.g. structural shocks related to increased housing demand and commodity price booms)
 - One must disentangle monetary policy shocks from other structural shocks in order to assess the relative importance of monetary policy

What is a VAR

- Suppose we have data on C (consumption) and Y (output). The VAR model of order 1 (VAR(1)) is written as:

$$\begin{aligned}C_t &= \lambda + \beta_1 C_{t-1} + \beta_2 Y_{t-1} + e_t \\Y_t &= \alpha + \rho_1 C_{t-1} + \rho_2 Y_{t-1} + \nu_t \\ \Sigma &= E(e_t, \nu_t)\end{aligned}\tag{1.1}$$

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- Each variable depends on the lags of the two \rightarrow each variable is endogenous

Estimating a VAR model

- Just N linear regression
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$$Y = \begin{pmatrix} C_2 & Y_2 \\ C_3 & Y_3 \\ \vdots & \vdots \\ C_T & Y_T \end{pmatrix}, \quad X = \begin{pmatrix} 1 & C_1 & Y_1 \\ 1 & C_2 & Y_2 \\ 1 & \vdots & \vdots \\ 1 & C_{T-1} & Y_{T-1} \end{pmatrix}$$

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- The residuals are used to estimate the variance-covariance matrix:

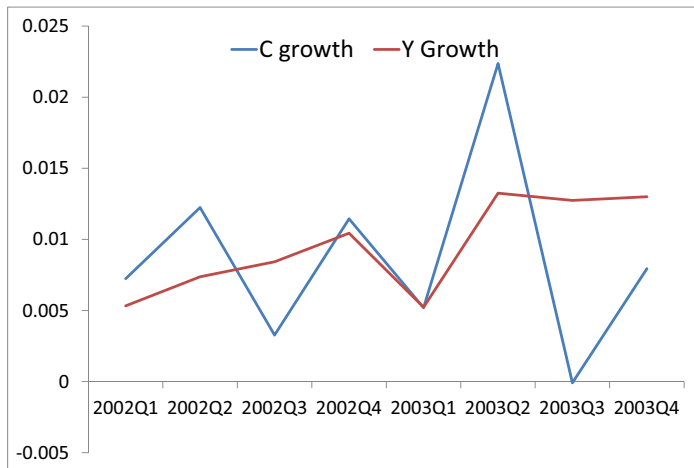
$$\Omega = Y - X\hat{B} \quad (1.3)$$

$$\Sigma = \frac{\Omega'\Omega}{T - K}$$

Estimating a VAR model

Illustration

Figure : Growth of real consumption and output in the UK, 2002Q1-2003Q4



Estimating a VAR model

Illustration

- The data:

$$UK \text{ Data} = \begin{bmatrix} \textit{Period} & \textit{C growth} & \textit{Y growth} \\ 2002Q1 & 0.0072 & 0.0053 \\ 2002Q2 & 0.0122 & 0.0073 \\ 2002Q3 & 0.0032 & 0.0084 \\ 2002Q4 & 0.0114 & 0.0104 \\ 2003Q1 & 0.0051 & 0.0052 \\ 2003Q2 & 0.0223 & 0.0132 \\ 2003Q3 & -8.8E - 05 & 0.0127 \\ 2003Q4 & 0.0079 & 0.0129 \end{bmatrix} \quad (1.4)$$

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- Y and X matrices:

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- Using the data matrices covering 7 quarters:

$$\hat{B} = \begin{bmatrix} 0.024 & 0.008 \\ -0.46 & -0.09 \\ 1.254 & 0.309 \end{bmatrix} \quad (1.7)$$

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- Plug the estimates back into our VAR model 1.1:

$$\begin{aligned} C_t &= 0.024 - 0.46C_{t-1} + 1.254Y_{t-1} + e_t \\ Y_t &= 0.008 - 0.09C_{t-1} + 0.309Y_{t-1} + \nu_t \end{aligned} \quad (1.8)$$

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- Model Selection Criteria (AIC, SIC etc) and LR tests
- Degrees of freedom \rightarrow a lot of coefficients can lead to imprecise estimates

Lag length in a VAR

- Total number of parameters, K , in a VAR with
 - N number of endogenous variables, and
 - P number of lags

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- For example, with $N = 4$ and $P = 4$, the number of parameters is $K = 68!$
- If time series is short, then the choice of P is crucial:

$$\begin{aligned} AIC &= \ln \det(\Sigma) + \frac{2N^2P}{T} \\ SIC &= \ln \det(\Sigma) + \frac{N^2P \ln T}{T} \end{aligned} \quad (1.10)$$

- Choose smallest AIC/SIC after estimating from $P = 1 \dots p$

Inference VARs: Impulse Response Functions

- Consider our VAR(1) model:

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- Assume the coefficients are known: What is the impact on C if there is a shock to Y ?

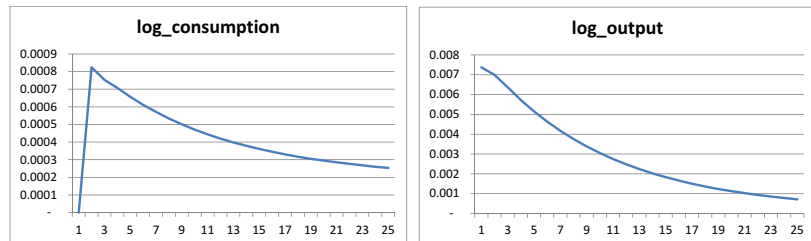
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- Assume the coefficients are known: What is the impact on C if there is a shock to Y ?
- The impact of this is referred to as the impulse response function (IRF)

Figure : Example for IRFs



Impulse Response Functions

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$$\begin{aligned}y_t &= c_1 + b_{11}y_{t-1} + b_{12}x_{t-1} + \nu_{1,t} \\x_t &= c_2 + b_{21}y_{t-1} + b_{22}x_{t-1} + \nu_{2,t}\end{aligned}\tag{2.2}$$

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- Consider the following experiment:
 - Time 0: both y and x are zero and $c = 0$
 - Time 1: one unit increase in x

Impulse Response Functions

Tracing out the impact

- Initial Shock:

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- Period 2:

$$\begin{pmatrix} y_2 \\ x_2 \end{pmatrix} = \begin{pmatrix} b_{11} & b_{12} \\ b_{21} & b_{22} \end{pmatrix} \begin{pmatrix} y_1 \\ x_1 \end{pmatrix} = \begin{pmatrix} b_{11}y_1 + b_{12}x_1 \\ b_{21}y_1 + b_{22}x_1 \end{pmatrix} = \begin{pmatrix} b_{12} \\ b_{22} \end{pmatrix} \quad (2.5)$$

Impulse Response Functions

- Period 3:

$$\begin{pmatrix} y_3 \\ x_3 \end{pmatrix} = \begin{pmatrix} b_{11} & b_{12} \\ b_{21} & b_{22} \end{pmatrix} \begin{pmatrix} y_2 \\ x_2 \end{pmatrix} \quad (2.6)$$

$$\begin{pmatrix} y_3 \\ x_3 \end{pmatrix} = \begin{pmatrix} b_{11} & b_{12} \\ b_{21} & b_{22} \end{pmatrix}^2 \begin{pmatrix} y_1 \\ x_1 \end{pmatrix} \quad (2.7)$$

$$\begin{pmatrix} y_3 \\ x_3 \end{pmatrix} = \begin{pmatrix} b_{11}^2 + b_{12}b_{21} & b_{11}b_{12} + b_{12}b_{22} \\ b_{21}b_{11} + b_{22}b_{21} & b_{21}b_{12} + b_{22}^2 \end{pmatrix} \begin{pmatrix} y_1 \\ x_1 \end{pmatrix} \quad (2.8)$$

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- The impulse response for period i is:

$$\begin{pmatrix} b_{11} & b_{12} \\ b_{21} & b_{22} \end{pmatrix}^{i-1} \quad (2.10)$$

- VARs are useful for forecasting as all variables are endogenous:

$$\begin{aligned} \begin{pmatrix} \hat{Y}_{T+1} \\ \hat{C}_{T+1} \end{pmatrix} &= \begin{pmatrix} \hat{b}_{11} & \hat{b}_{12} \\ \hat{b}_{21} & \hat{b}_{22} \end{pmatrix} \begin{pmatrix} Y_T \\ C_T \end{pmatrix} \\ \begin{pmatrix} \hat{Y}_{T+2} \\ \hat{C}_{T+2} \end{pmatrix} &= \begin{pmatrix} \hat{b}_{11} & \hat{b}_{12} \\ \hat{b}_{21} & \hat{b}_{22} \end{pmatrix} \begin{pmatrix} \hat{Y}_{T+1} \\ \hat{C}_{T+1} \end{pmatrix} \\ &\vdots \end{aligned} \tag{3.1}$$

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- Useful as a short term forecasting tool \rightarrow but little theoretical underpinning

- Conditional forecasting is a useful application
- Assume some of the variables in the VAR are exogenous in the future (e.g. pegged interest rate)
- These may be variables for which data is more readily available or a future path of these variables is available

Conditional Forecasting

- Consider a simple VAR:

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- In conditional forecasts we calculate future shocks that give us the constrained forecast (e.g. Compass - BoE forecasting platform)

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- Imagine you make a forecast for the variables in the VAR
- Because of shocks, there will be an error in forecasting
- FEVD refers to working out how much each shock contributed to the forecast error variance

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- The variables are going to be hit by the two shocks in our model
- The IRF and the scale of the shocks will determine how much each variable moves

$$\begin{aligned}C_t &= \lambda + \beta_1 C_{t-1} + \beta_2 Y_{t-1} + e_t \\ Y_t &= \alpha + \rho_1 C_{t-1} + \rho_2 Y_{t-1} + \nu_t\end{aligned}\tag{4.1}$$

Table : Shock contributions

Shock	e_t	ν_t
Movement in period 1	$\sigma_e \Psi_{e,1}$	$\sigma_\nu \Psi_{\nu,1}$
Contribution to variance	$(\sigma_e \Psi_{e,1})^2$	$(\sigma_\nu \Psi_{\nu,1})^2$

Forecast Error Variance Decomposition (FEVD)

- 2 periods in the future – impact of the shocks in period 1 and period 2 and so on

Table : Shock contributions

Shock	e_t	ν_t
Movement in period 2	$\sigma_e \Psi_{e,1} + \sigma_e \Psi_{e,2}$	$\sigma_\nu \Psi_{\nu,1} + \sigma_\nu \Psi_{\nu,2}$
Contribution to variance	$(\sigma_e \Psi_{e,1})^2 + (\sigma_e \Psi_{e,2})^2$	$(\sigma_\nu \Psi_{\nu,1})^2 + (\sigma_\nu \Psi_{\nu,2})^2$

Historical Decomposition

$$\begin{pmatrix} y_t \\ x_t \end{pmatrix} = \begin{pmatrix} b_{11} & b_{12} \\ b_{21} & b_{22} \end{pmatrix} \begin{pmatrix} y_{t-1} \\ x_{t-1} \end{pmatrix} + \begin{pmatrix} c_1 \\ c_2 \end{pmatrix} + \begin{pmatrix} \nu_{1,t} \\ \nu_{2,t} \end{pmatrix} \quad (5.1)$$

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Historical Decomposition

- Historical decomposition measures the contribution of each shock to the level of each series:

$$\begin{aligned} \begin{pmatrix} y_t \\ x_t \end{pmatrix} &= \overbrace{\sum_{i=0}^{T-1} \begin{pmatrix} b_{11} & b_{12} \\ b_{21} & b_{22} \end{pmatrix}^i \begin{pmatrix} c_1 \\ c_2 \end{pmatrix}}^{\text{Base or trend}} + \begin{pmatrix} b_{11} & b_{12} \\ b_{21} & b_{22} \end{pmatrix}^T \begin{pmatrix} y_0 \\ x_0 \end{pmatrix} \\ &+ \underbrace{\sum_{i=0}^{T-1} \begin{pmatrix} b_{11} & b_{12} \\ b_{21} & b_{22} \end{pmatrix}^i \begin{pmatrix} \nu_{1,t-i} \\ \nu_{2,t-i} \end{pmatrix}}_{\text{Contributions of the 2 shocks}} \end{aligned} \quad (5.4)$$

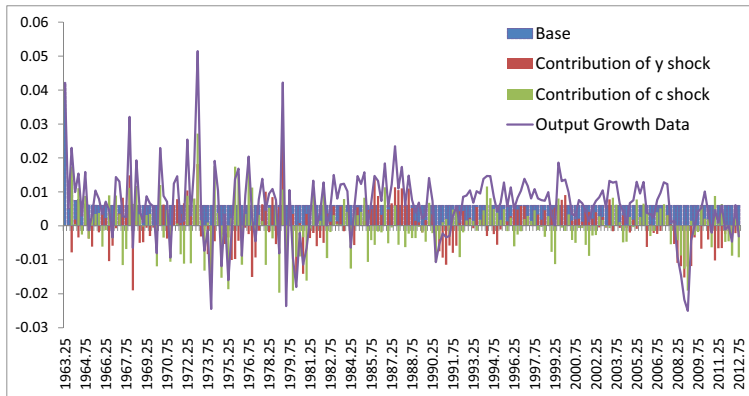
Historical Decomposition

- Historical decomposition presented as bar chart where the bars represent contribution by the shocks and the trend

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Figure : Example for Historical Decomposition



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- Identification is needed to “make structural shocks out of” reduced-form residuals
- Structural VARs make various identification assumptions to achieve meaningful decompositions

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